

# Soumo Roy

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## EDUCATION

### Vellore Institute of Technology (VIT)

Bachelor of Technology in Electronics and Communication Engineering

CGPA: 8.83/10 (Top 10% of the batch)

Vellore, Tamil Nadu, India

July 2021 - May 2025

## TECHNICAL SKILLS

**Programming Languages:** Python, C++ , MATLAB, LaTeX

**AI/ML Libraries and Developers Tools:** PyTorch, Pandas, Numpy, OpenCV, Git, Docker, Linux(Ubuntu)

**Simulation Packages:** ROS1, ROS2, Gazebo, RVIZ, MuJoCo, pybullet, OpenAI Gym

**Hardware/Boards:** NVIDIA Jetson Nano, Intel Atom, Arduino , Raspberry Pi, STM32 , ESP32

## WORK EXPERIENCE

### Research Assistant

IIIT Hyderabad, Telangana, India

January 2025 - present

- \* Working under Dr Madhava Krishna at RRC (Robotics Research Center) at IIIT Hyderabad
- \* Implemented a path planner for an autonomous wheelchair for navigating in crowded environments using generative AI (VQ-VAE and PixelCNN) with a novel sampling optimiser which improved efficiency by 40% compared to state of the art learning based approaches.

### SN Bose Summer Research Intern

NIT Silchar, Assam, India

June 2024 - July 2024

- \* Worked under Dr Yogesh Singh at Advanced Robotics Research Lab, NIT Silchar
- \* Collaborated on a MATLAB simulation of shape memory alloy(SMA) based assistive robotic glove simulation for patients with wrist mobility issues, which reduced strain by 78%.

### SURGE Research Intern

IIT Kanpur, Uttar Pradesh, India

May 2024 – June 2024

- \* Guided by Dr. Tushar Sandhan and Mr. Prem Raj at Intelligent System Control Lab, IIT Kanpur
- \* Contributed to a human robot collaboration project using imitation learning with UR5 collaborative robot and Intel RealSense camera for the collaborative action of heavy object lifting with an efficiency of 68% compared to reinforcement learning approaches.
- \* Was one among 42 students selected under the institute project funded category at the IIT Kanpur

### Robotics System Validation Intern

Unbox Robotics, Maharashtra, India

August 2023 – November 2023

- \* Developed a project to automate the testing of the web page used for controlling robots using webdriver.io and JavaScript, Docker and deployed it on GitLab CI/CD pipeline, which improved validation teams' testing efficiency by 20%.

## PROJECTS

- **Spoon feeder**, Implemented reinforcement learning algorithms (PPO, SAC and DDPG) across different manipulators simulating feeding and drinking tasks on OpenAI gym, which was published in IEEE INDICON-24 conference [GitHub](#)
- **Crowdsurfer-ROS**, Utilized generative AI with sampling optimiser for path planning for a mobile robot to navigate in a crowded environment with dynamic obstacles, won best bachelor thesis award for the project [GitHub](#)
- **Eyantra Robotics Competition (IIT Bombay)**, Navigated a mobile robot with the help of SLAM algorithms in a warehouse by detecting and localising the packages placed on racks, and manipulating the robotic arm to pick them up where we were among the top 5 performing teams to represent our college at IIT Bombay. [GitHub](#)

## PUBLICATIONS

- **S. Roy, J. Viju, B. Bhattacharya**, "Adaptive Robotic Manipulator Simulation for Enhanced Feeding and Drinking Assistance", 21st IEEE INDICON-2024 DOI: 10.1109/INDICON63790.2024.10958301 [Link](#)
- **S. Chowdhury, S. Roy, D. G. Chowdhury, S. Chakraborty, B. Bhattacharya**, "SKIDS: An Object Classification and Smart Communication based Waste Bin", 3rd IEEE AIIoT-2024 DOI: 10.1109/AIIoT58432.2024.10574647 [Link](#)

## ACHIEVEMENTS

- Featured in Telangana state newspaper during R&D showcase 2025, and attracted more than 300+ visitors to our poster based on my bachelor thesis [\(link\)](#)
- Won a seed grant of **Rs 1.5 lakh (\$1790)** from VIT faculty-student sponsored project fund for a medical assistive robot project under Dr. Budhaditya Bhattacharyya at Advance Digital Signal Processing Lab as a part of my final year project [Link](#)